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# **DEPARTMENT OF ELECTRICAL ENGINEERING**

## **Govt. Polytechnic, Balasore**

### **LESSON PLAN FOR ACADEMIC SESSION - 2023-24 CONTROL SYSTEM ENGINEERING**

|   |  |
|---|--|
| <b>Course Code : Th-3</b>                             | <b>Semester : 6<sup>TH</sup></b>           |
| <b>Total Periods : 75(60L+15T)</b>                    | <b>Examination : 3 Hours</b>               |
| <b>Theory Periods : 4 P/Week</b>                      | <b>Internal Assessment : 20 Marks</b>      |
| <b>Tutorial : 1 P/Week</b>                            | <b>End Semester Examination : 80 Marks</b> |
| <b>Maximum Marks : 100</b>                            |  |
| <b>Semester From Date : 16/01/2024</b>                | <b>To Date : 8/05/2024</b>                 |
| <b>Name of Teaching Faculty: Er. Radha Rani Panda</b> |  |

| WEEK            | PERIOD          | TOPIC   |
|-----------------|-----------------|---|
| 1 <sup>st</sup> | 1 <sup>st</sup> | <b>FUNDAMENTAL OF CONTROL SYSTEM</b><br>Classification of Control system<br>Open loop system & Closed loop system and its comparison          |
|                 | 2 <sup>nd</sup> | Effects of Feed back  |
|                 | 3 <sup>rd</sup> | Standard test Signals(Step, Ramp, Parabolic, Impulse Functions)   |
|                 | 4 <sup>th</sup> | Servomechanism  |
|                 | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )   |
| 2 <sup>nd</sup> | 1 <sup>st</sup> | <b>MATHEMATICAL MODEL OF A SYSTEM</b><br>Transfer Function & Impulse response,<br>Properties, Advantages & Disadvantages of Transfer Function |
|                 | 2 <sup>nd</sup> | Poles & Zeroes of transfer Function   |
|                 | 3 <sup>rd</sup> | Simple problems of transfer function of network.  |
|                 | 4 <sup>th</sup> | Mathematical modeling of Electrical Systems(R, L, C, Analogous systems)   |
|                 | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )   |
| 3 <sup>rd</sup> | 1 <sup>st</sup> | <b>CONTROL SYSTEM COMPONENTS</b><br>Components of Control System<br>Gyroscope,  |
|                 | 2 <sup>nd</sup> | Synchros, Tachometer  |
|                 | 3 <sup>rd</sup> | DC servomotors  |
|                 | 4 <sup>th</sup> | Ac Servomotors  |
|                 | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )   |
| 4 <sup>th</sup> | 1 <sup>st</sup> | <b>BLOCK DIAGRAM ALGEBRA &amp; SIGNAL FLOW</b>  |

|                  |                 |  |
|------------------|-----------------|--|
|                  |                 | <b>GRAPHS</b><br>Definition: Basic Elements of Block Diagram<br>Canonical Form of Closed loop Systems                                  |
|                  | 2 <sup>nd</sup> | Rules for Block diagram reduction  |
|                  | 3 <sup>rd</sup> | Procedure for of Reduction of Block Diagram  |
|                  | 4 <sup>th</sup> | Simple Problem for equivalent transfer function  |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )  |
| 5 <sup>th</sup>  | 1 <sup>st</sup> | Basic Definition in Signal Flow Graph & properties   |
|                  | 2 <sup>nd</sup> | Construction of Signal Flow graph from Block diagram   |
|                  | 3 <sup>rd</sup> | Mason's Gain formula   |
|                  | 4 <sup>th</sup> | Simple problems in Signal flow graph for network   |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )  |
| 6 <sup>th</sup>  | 1 <sup>st</sup> | <b>TIME RESPONSE ANALYSIS.</b><br>Time response of control system.<br>Standard Test signal.<br>Step signal,                            |
|                  | 2 <sup>nd</sup> | Ramp Signal<br>Parabolic Signal<br>Impulse Signal  |
|                  | 3 <sup>rd</sup> | Time Response of first order system with:<br>Unit step response<br>Unit impulse response   |
|                  | 4 <sup>th</sup> | Time response of second order system to the unit step input.<br>Time response specification.<br>Derivation of expression for rise time |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )  |
| 7 <sup>th</sup>  | 1 <sup>st</sup> | Derivation of expression for peak time, peak overshoot, settling time and steady state error   |
|                  | 2 <sup>nd</sup> | Steady state error and error constants   |
|                  | 3 <sup>rd</sup> | Types of control system.[ Steady state errors in Type-0, Type-1]   |
|                  | 4 <sup>th</sup> | Steady state errors in Type-2 system]<br>Effect of adding poles and zero to transfer function.   |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing, Numericals and revision class</b> )  |
| 8 <sup>th</sup>  | 1 <sup>st</sup> | Response with P, PI controller   |
|                  | 2 <sup>nd</sup> | Response with PD and PID controller  |
|                  | 3 <sup>rd</sup> | <b>ANALYSIS OF STABILITY BY ROOT LOCUS TECHNIQUE.</b><br>Root locus concept  |
|                  | 4 <sup>th</sup> | Construction of root loci.   |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing, Numericals and revision class</b> )  |
| 9 <sup>th</sup>  | 1 <sup>st</sup> | Construction of root loci..  |
|                  | 2 <sup>nd</sup> | Rules for construction of the root locus.  |
|                  | 3 <sup>rd</sup> | Rules for construction of the root locus.  |
|                  | 4 <sup>th</sup> | Problems related to Root Locus   |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )  |
| 10 <sup>th</sup> | 1 <sup>st</sup> | Problems related to Root Locus   |
|                  | 2 <sup>nd</sup> | Effect of adding poles and zeros to G(s) and H(s).   |
|                  | 3 <sup>rd</sup> | Problems related to Root Locus   |
|                  | 4 <sup>th</sup> | Problems related to Root Locus   |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )  |
| 11 <sup>th</sup> | 1 <sup>st</sup> | <b>FREQUENCY RESPONSE ANALYSIS.</b>  |

|                  |                 |   |
|------------------|-----------------|---|
|                  |                 | Correlation between time response and frequency response                        |
|                  | 2 <sup>nd</sup> | Polar plots.  |
|                  | 3 <sup>rd</sup> | Problems related to Polar plots.  |
|                  | 4 <sup>th</sup> | Bode plots.   |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )                           |
| 12 <sup>th</sup> | 1 <sup>st</sup> | Problems related to Bode plots  |
|                  | 2 <sup>nd</sup> | All pass and minimum phase system.  |
|                  | 3 <sup>rd</sup> | Computation of Gain margin and phase margin.                                    |
|                  | 4 <sup>th</sup> | Problems related to computation of Gain margin and phase margin                 |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )                           |
| 13 <sup>th</sup> | 1 <sup>st</sup> | Log magnitude versus phase plot.  |
|                  | 2 <sup>nd</sup> | Closed loop frequency response.   |
|                  | 3 <sup>rd</sup> | <b>NYQUIST PLOT</b><br>Principle of argument                                    |
|                  | 4 <sup>th</sup> | Nyquist stability criterion.  |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )                           |
| 14 <sup>th</sup> | 1 <sup>st</sup> | Problems related to Niquist stability   |
|                  | 2 <sup>nd</sup> | Niquist stability criterion applied to inverse polar plot.                      |
|                  | 3 <sup>rd</sup> | Problems related to inverse polar plot.   |
|                  | 4 <sup>th</sup> | Effect of addition of poles and zeros to G(S) H(S) on the shape of Niquist plot |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )                           |
| 15 <sup>th</sup> | 1 <sup>st</sup> | Assessment of relative stability.   |
|                  | 2 <sup>nd</sup> | Constant M circle   |
|                  | 3 <sup>rd</sup> | Constant N circle   |
|                  | 4 <sup>th</sup> | Nicholas chart.   |
|                  | 5 <sup>th</sup> | Tutorial ( <b>Doubt clearing and revision class</b> )                           |